

2D Motion

Set 1

- ① Velocity vector of a particle is given as $\mathbf{v} = 4t\hat{i} + 3\hat{j}$. At $t = 0$, position of the particle is given as $\mathbf{r}_0 = 2\hat{j}$. Find the position vector of the particle at $t = 2$ s.
 (a) $\mathbf{r} = 8\hat{i} + 4\hat{j}$ (b) $\mathbf{r} = 4\hat{i} + 4\hat{j}$ (c) $\mathbf{r} = 8\hat{i} + 8\hat{j}$ (d) $\mathbf{r} = 4\hat{i} + 8\hat{j}$

- ② A particle moves in the xy -plane and its coordinates are given by $x = k \sin \omega t$ and $y = k(1 - \cos \omega t)$, where k and ω are constants. What is the magnitude of acceleration of the particle?
 (a) Zero (b) $k\omega$ (c) $k\omega^2$ (d) $k^2\omega$

- ③ A point moves in the xy -plane according to the law $x = 3t$ and $y = 3t\left(1 - \frac{t}{4}\right)$ where x, y are in metre and t is in second. What is the time (in second) after which velocity makes an angle of $\frac{\pi}{4}$ with the acceleration?

- ④ From point A located on a highway (figure) one has to get by car as soon as possible to point B located in the field at a distance $l = 3\sqrt{2}$ km from the highway. It is known that the car moves in the field 3 times slower than on the highway.
 At what distance (in km) from point D one must turn off the highway?



- ⑤ A particle projected from the origin ($x = y = 0$) moves in xy -plane, so that its velocity is $\mathbf{v} = (2\hat{i} + 4x\hat{j})$ m/s, when it is at the point (x, y) m. What is the value of y when $x = 3$?

- ⑥ A point moves in the xy -plane according to the law $x = \alpha t$ and $y = \alpha t(1 - \beta t)$, where α and β are positive constants. The time after which the velocity makes an angle $\frac{\pi}{4}$ with the acceleration is
 (a) $\frac{1}{\alpha}$ (b) $\frac{1}{\beta}$ (c) $\frac{2}{\beta}$ (d) $\frac{2}{\alpha}$

- ⑦ A particle moves uniformly with speed v along the parabolic path $y = kx^2$, where k is a positive constant. The acceleration of the particle at $x = 0$ is given by
 (a) $2kv^2$ (b) kv^2 (c) $\frac{1}{2}kv^2$ (d) $2kv$

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Methods and Protocols Ray H. Gavin, 2008-02-03 Over the past two decades experimental studies have solidified the interpretation of the cytoskeleton as a highly dynamic network of microtubules actin microfilaments intermediate filaments and myosin filaments Rather than a network of disparate fibers these polymers are often interconnected and display synergy which is the combined action of two or more cytoskeletal polymers to achieve a specific cellular structure or function Cross communication among cytoskeletal polymers is thought to be achieved through cytoskeletal polymer accessory proteins and molecular motors that bind two or more cytoskeletal polymers Development of the modern concept of the cytoskeleton is a direct result of growth of advances in experimental tools and reagents that are available to cell and molecular biologists Technological advances and refinements in cell imaging have made it possible to selectively image a single cytoskeletal polymer and monitor its dynamics through the use of fluorescence probes in vitro and in vivo Two decades ago cytoskeletal research was limited to a few perturbation reagents that included colchicine and cytochalasin Today the perturbation arsenal has expanded to a highly selective group of reagents that includes Taxol nocodazole benomyl latrunculin jasplakinolide and such endogenous proteins as gelsolin These reagents enable the investigator to selectively perturb or destroy a cytoskeletal polymer while leaving other cytoskeletal polymers intact Site specific monoclonal antibodies that target a specific cytoskeletal polymer have proven to be highly selective affinity tools for cytoskeletal research *1997 Symposium on*

Interactive 3D Graphics, 1997 **The 1995 Goddard Conference on Space Applications of Artificial Intelligence and Emerging Information Technologies** Carl F. Hostetter, 1995 *Vibration Theory and Applications with Finite Elements and Active Vibration Control* Alan B. Palazzolo, 2016-01-11 Based on many years of research and teaching this book brings together all the important topics in linear vibration theory including failure models kinematics and modeling unstable vibrating systems rotordynamics model reduction methods and finite element methods utilizing truss beam membrane and solid elements It also explores in detail active vibration control instability and modal analysis The book provides the modeling skills and knowledge required for modern engineering practice plus the tools needed to identify formulate and solve engineering problems effectively *Cahill-Parsons New York Civil Practice* New York (State), 1963 *Biologically Inspired Computer Vision* Gabriel Cristobal, Laurent Perrinet, Matthias S. Keil, 2015-08-20 As the state of the art imaging technologies became more and more advanced yielding scientific data at unprecedented detail and volume the need to process and interpret all the data has made image processing and computer vision increasingly important Sources of data that have to be routinely dealt with today's applications include video transmission wireless communication automatic fingerprint processing massive databanks non weary and accurate automatic airport screening robust night vision just to name a few Multidisciplinary inputs from other disciplines such as physics computational neuroscience cognitive science mathematics and biology will have a fundamental impact in the progress of imaging and vision sciences One of the advantages of the study of biological organisms is to devise very different type of computational paradigms by implementing a neural network with a high degree of local connectivity This is a comprehensive and rigorous reference in the area of biologically motivated vision sensors The study of biologically visual systems can be considered as a two way avenue On the one hand biological organisms can provide a source of inspiration for new computational efficient and robust vision models and on the other hand machine vision approaches can provide new insights for understanding biological visual systems Along the different chapters this book covers a wide range of topics from fundamental to more specialized topics including visual analysis based on a computational level hardware implementation and the design of new more advanced vision sensors The last two sections of the book provide an overview of a few representative applications and current state of the art of the research in this area This makes it a valuable book for graduate Master PhD students and also researchers in the field *Comprehensive Atlas of 3D Echocardiography* Roberto M. Lang, Stanton K. Shernan, Stanton Shernan, 2012-12-24 The Comprehensive Atlas of 3D Echocardiography takes full advantage of today's innovative multimedia technology To help the reader understand the unique dynamic nature of a comprehensive 3D echocardiographic examination the printed pages are supplemented with a companion website this Atlas introduces the use of anatomy specimens videos unique imaging windows and novel displays obtained with cropping tools This approach offers a clear picture of how the diagnostic and monitoring capabilities of 3D echocardiography can benefit patients with a wide range of cardiovascular pathology including congenital heart disease By

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Imaging and Computer-Assisted Interventions Hongen Liao,Cristian A Linte,Ken Masamune,Terry M. Peters,Guayan Zheng,2013-09-18 This book constitutes the refereed proceedings of two workshops MAIR AE CAI 2013 held in conjunction with MICCAI 2013 held in Nagoya Japan in September 2013 The 29 revised full papers presented were carefully reviewed and selected from 44 submissions The papers cover a wide range of topics addressing the main research efforts in the fields of medical image formation analysis and interpretation augmented reality and visualization computer assisted intervention interventional imaging image guided robotics image guided intervention surgical planning and simulation systematic extra and intra corporeal imaging modalities and general biological and neuroscience image computing *Tax Court Digest*

United States. Tax Court,1951 Scientific and Technical Aerospace Reports ,1994 The Law Times ,1865 Decisions and Orders of the National Labor Relations Board United States. National Labor Relations Board,1985-02 Aspects of Ergodic, Qualitative and Statistical Theory of Motion Giovanni Gallavotti,Federico Bonetto,Guido Gentile,2013-03-09

Intended for beginners in ergodic theory this book addresses students as well as researchers in mathematical physics The main novelty is the systematic treatment of characteristic problems in ergodic theory by a unified method in terms of convergent power series and renormalization group methods in particular Basic concepts of ergodicity like Gibbs states are developed and applied to e g Asonov systems or KAM Theory Many examples illustrate the ideas and in addition a substantial number of interesting topics are treated in the form of guided problems **Catalog of Copyright Entries. Third Series**

Library of Congress. Copyright Office,1955 **Proceedings of the General Time Convention and Its Successor the American Railway Association** Association of American Railroads,1910 Vol 1 contains proceedings of the earlier organizations known as the General Time Convention 1872 to 1885 and the Southern Railway Time Convention 1877 to 1885

The Neurocognition of Dance Bettina Bläsing,Martin Puttke,Thomas Schack,2010-07-02 Dance has always been an important aspect of all human cultures and the study of human movement and action has become a topic of increasing relevance This book discusses the wide range of interrelations between body postures and body movements as conceptualised in dance with perception mental processing and action planning

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